

# Lecture 01

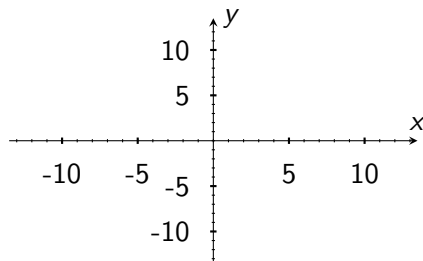
## 12.1/12.2 The geometry of space and vectors

Jeremiah Southwick

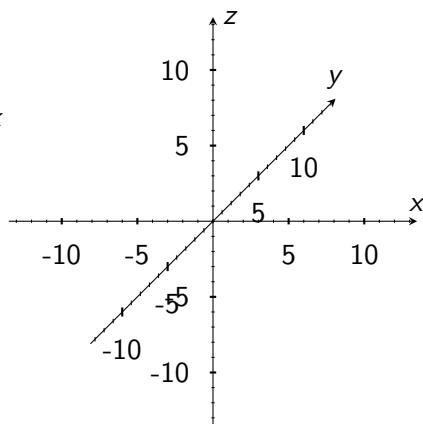
January 14, 2019

## §12.1 Plane vs. Space

Plane

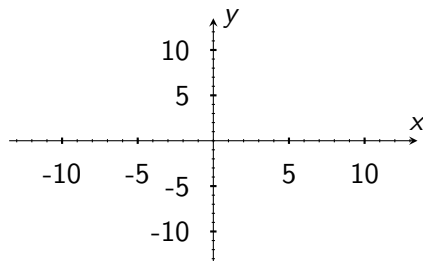


Space

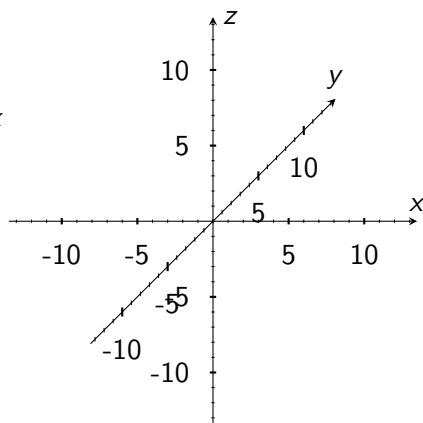


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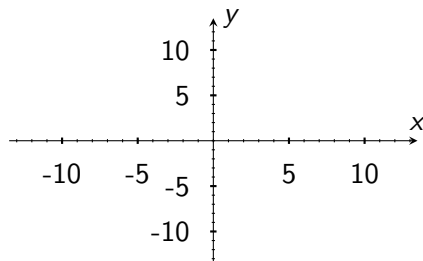
Space



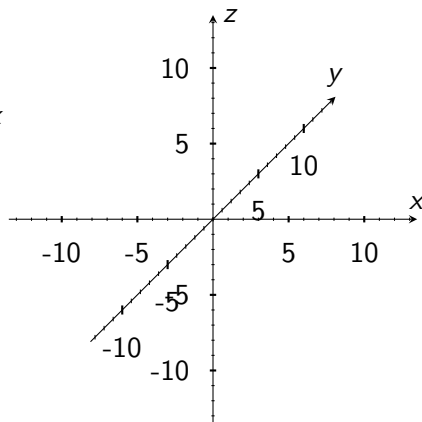
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Plane



Space



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We always draw the coordinate axes using the right-hand rule.

## Plane vs. Space

Since we have three variables, points are represented as triplets.

Plane  
 $(x, y)$

Space  
 $(x, y, z)$

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We can use online tools to visualize these objects.

<https://www.geogebra.org/3d?lang=en>

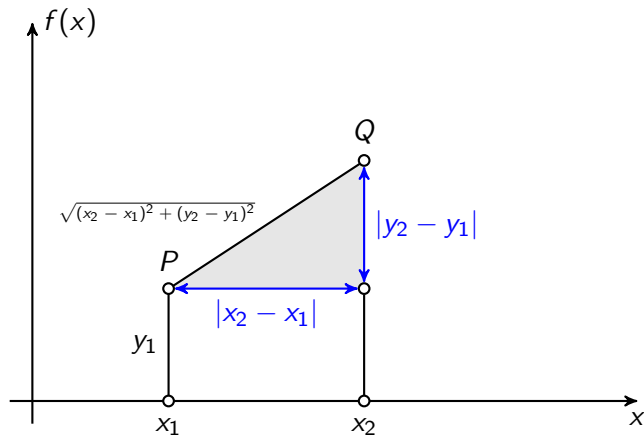


# Distance and Spheres

In two dimensions, distance is calculated using Pythagorean's theorem.

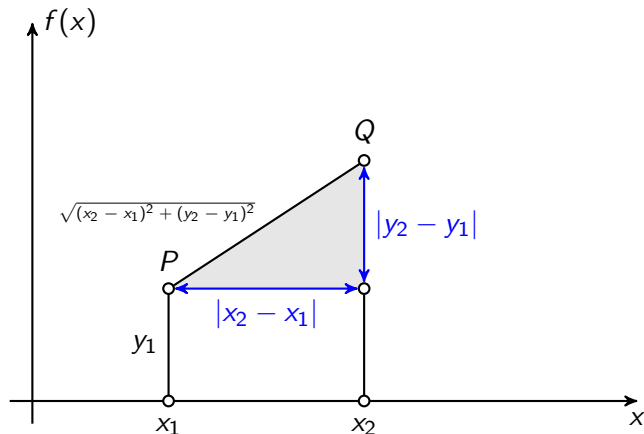
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A similar formula holds in 3D (and in higher dimensions).

# DISTANCE!

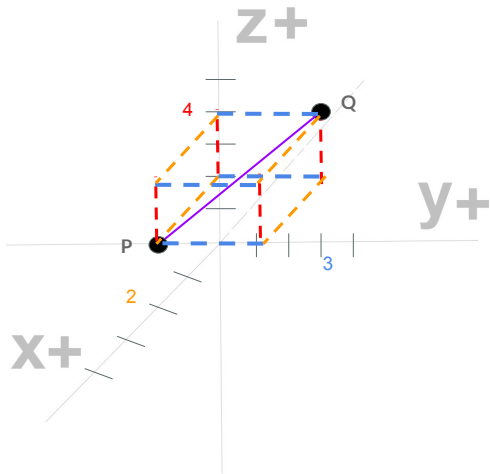
How do we find the distance between two points?

$$|PQ|=?$$

Let's try an example:

$$P=(2,0,2)$$

$$Q=(0,3,4)$$



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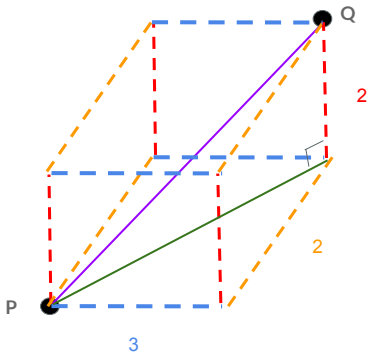
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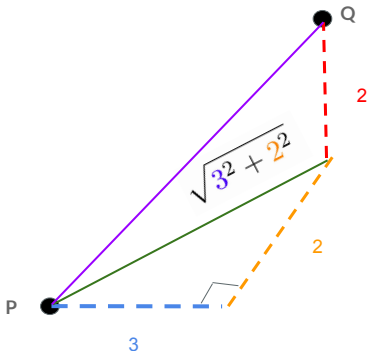
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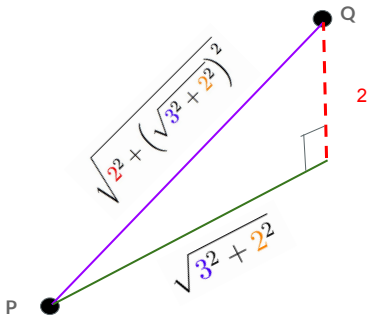
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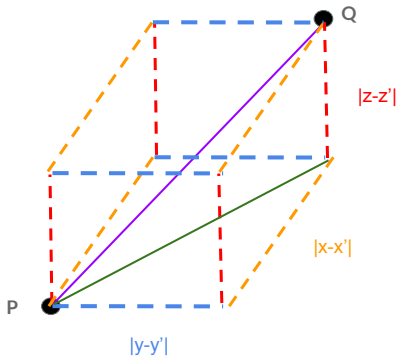
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In General:

$$P=(x,y,z)$$

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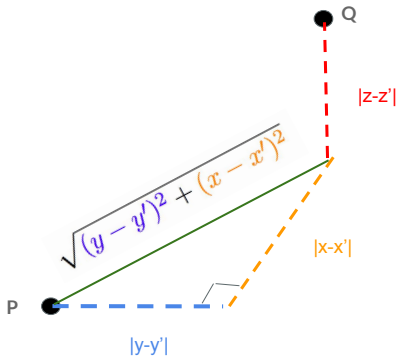
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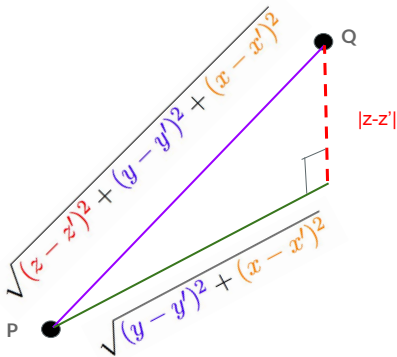
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# Distance and Spheres

Thus we have the following distance formula.

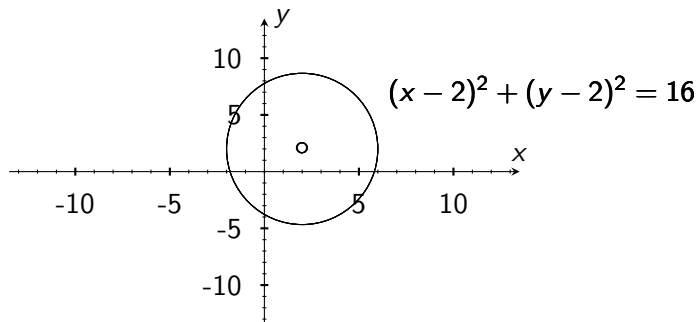
## Definition

*The distance between two points  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  is*

$$\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}.$$

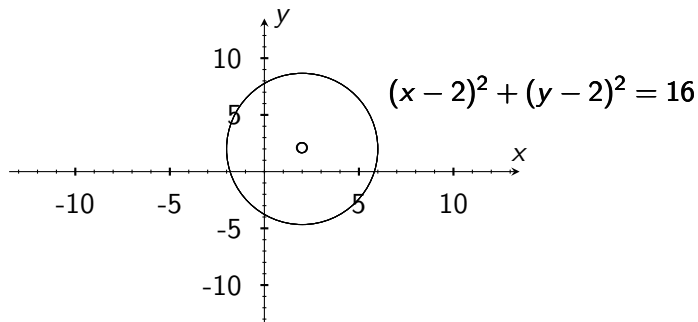
## Recall Circles

In the plane, a circle is all the points a fixed distance away from a fixed point.



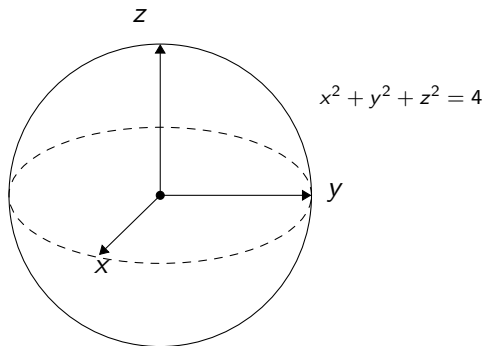
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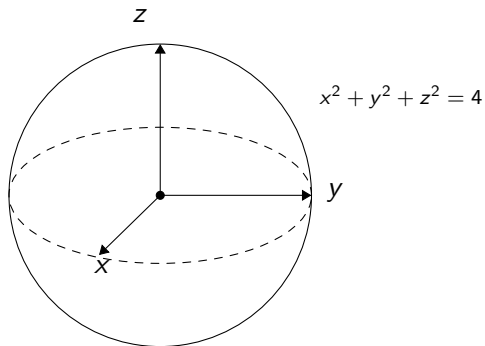


In space, the set of all points a fixed distance from a fixed point is a sphere.

# Spheres



# Spheres



Using the distance formula where we make  $(x, y, z)$  a point on the sphere with center  $(x_0, y_0, z_0)$  and radius  $r$ , we get the standard equation for a sphere.

# Spheres

If  $(x, y, z)$  has distance  $r$  from the center  $(x_0, y_0, z_0)$ , then the following equation holds:

$$\sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2} = r.$$



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To make it look nicer, we square both sides.

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## Definition

*The standard equation of a sphere with center  $(x_0, y_0, z_0)$  and radius  $r$  is*

$$(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2.$$

# Spheres

## Example

Find the center and radius of  $x^2 + y^2 + z^2 + 3x - 4z + 1 = 0$ .

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Find the center and radius of  $x^2 + y^2 + z^2 + 3x - 4z + 1 = 0$ .

We complete the square in each variable, adding the same amount to both sides of the equation:

$$\left[ x^2 + 3x + \left( \frac{3}{2} \right)^2 \right] + y^2 + \left[ z^2 - 4z + \left( -\frac{4}{2} \right)^2 \right] = -1 + \left( \frac{3}{2} \right)^2 + \left( -\frac{4}{2} \right)^2$$

This simplifies to

$$\left( x + \frac{3}{2} \right)^2 + y^2 + (z - 2)^2 = \frac{21}{4}.$$

Thus the sphere has center  $\left( -\frac{3}{2}, 0, 2 \right)$  and radius  $\sqrt{21/4}$ .

## §12.2 Vectors

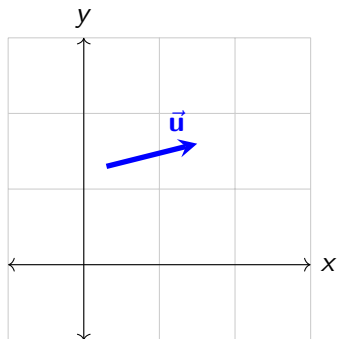
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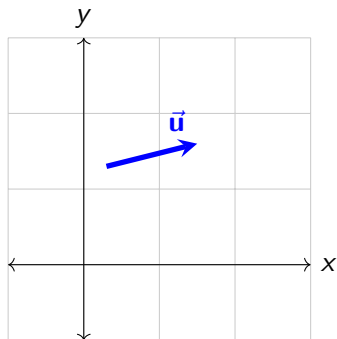
Put another way, a vector is the following information: A direction and a length/magnitude.



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The direction is where the arrow points and the length is how long the arrow is.



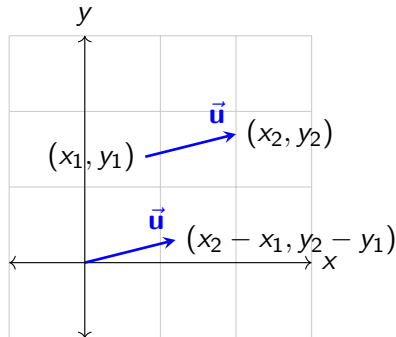
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A vector models any application where force is involved: velocity, displacement, work, etc.



Since it doesn't matter where we draw a vector, we will usually place the initial point at the origin. This is called *standard position*.

# Standard Position

## Definition

*If a vector  $\vec{v}$  goes from  $(x_1, y_1, z_1)$  to  $(x_2, y_2, z_2)$ , then the same vector in standard position goes from  $(0, 0, 0)$  to  $(x_2 - x_1, y_2 - y_1, z_2 - z_1)$ . In this case we write*

$$\vec{v} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle.$$

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$$\langle u_1, u_2, u_3 \rangle = \langle v_1, v_2, v_3 \rangle \Leftrightarrow u_1 = v_1, u_2 = v_2, \text{ and } u_3 = v_3$$

# Vectors

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*How would we write down the vector starting at  $(-7, 5, 0)$  and going to  $(3, -1, 4)$ ?*

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$$\vec{v} = \langle 10, -6, 4 \rangle.$$

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## Example

The length of  $\langle 7, 3, -2 \rangle$  is  $\sqrt{49 + 9 + 4} = \sqrt{62}$ .

# Zero Vector

The only vector with length 0 is the vector that starts at a point and ends at the same point. We have special notation for this vector.

## Definition

*The vector of all zeros is denoted  $\vec{\mathbf{0}} := \langle 0, 0, 0 \rangle$ . This notation can be used no matter what dimension, i.e., in 2D we have  $\vec{\mathbf{0}} = \langle 0, 0 \rangle$ .*